

# Hybrid dimensional two phase flows in fractured porous media

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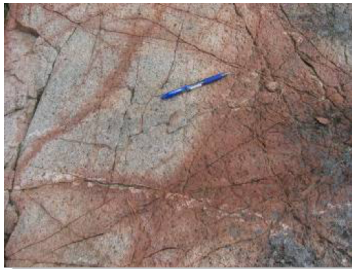
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# Outline

- Modelling Darcy flows in Discrete Fracture Networks
- The Vertex Approximate Gradient Discretization (VAG)
- Numerical Results

# Fractured porous media: multiple scales (figures from J. R. de Dreuzy, Geosciences Rennes and team INRIA Sage)

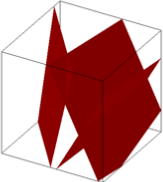
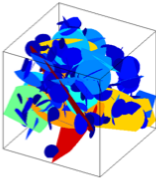
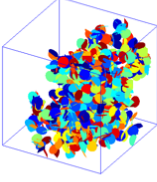
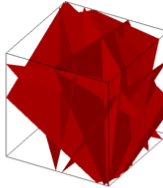
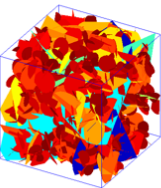
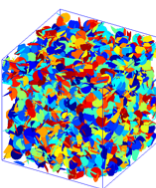


# Flow in Fractured porous media: two main approaches

- **Double Continuum Media**: 3D fracture medium coupled to 3D matrix medium
- **Discrete fracture models (DFM)**: 2D fracture model coupled to 3D matrix medium
- Possibility to couple both approaches
  - Double Continuum media for small fractures coupled with DFM for large fractures
  - Numerical Homogenization: parameters of the Double Continuum media computed by a DFM model

# Discrete fracture networks (DFN) (figures from J. R. de Dreuzy, Geosciences Rennes and team INRIA Sage)

## *Stochastic models of fractured media*

Crossing fractures "LONG"	Power-law length "DIST"	Small fractures "SHORT"	
			threshold
			"3*threshold"

# Modelling Darcy flows in Discrete Fracture Networks

# Equi-dimensional model in phase pressures formulation

**Two-phase Darcy law:**  $\mathbf{q}^\alpha = -k^\alpha(\mathbf{x}, S^\alpha(\mathbf{x}, p)) \Lambda(\mathbf{x})(\nabla u^\alpha - \rho^\alpha \mathbf{g})$ .

$\alpha = 1$  : wetting phase,  $\alpha = 2$  : non wetting phase

$\phi(\mathbf{x})$  : porosity

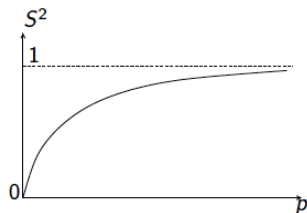
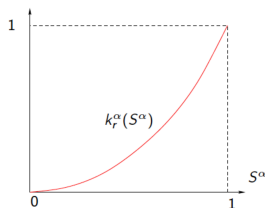
$\Lambda(\mathbf{x})$  : absolute permeability

$u^\alpha$  : phase pressure

$p = u^2 - u^1$  : capillary pressure

$S^2(\mathbf{x}, p)$  : inverse of capillary pressure graph,  $S^1(\mathbf{x}, p) = 1 - S^2(\mathbf{x}, p)$

$k^\alpha(\mathbf{x}, S^\alpha) = \frac{k_r^\alpha(\mathbf{x}, S^\alpha)}{\mu^\alpha}$  : phase mobility



# Equi-dimensional model in phase pressures formulation

**Two-phase Darcy law:**

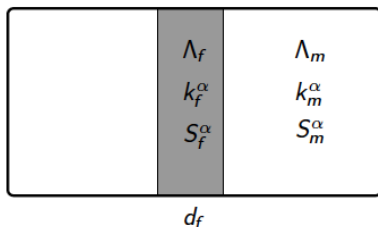
$$\mathbf{q}^\alpha = -k^\alpha(\mathbf{x}, S^\alpha(\mathbf{x}, p)) \Lambda(\mathbf{x})(\nabla u^\alpha - \rho^\alpha \mathbf{g}), \quad \alpha = 1, 2,$$

**Volume conservation for each phase:**

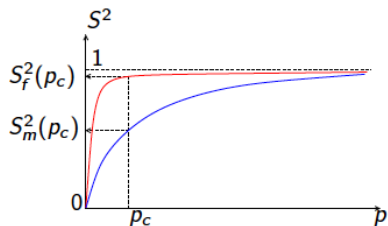
$$\phi(\mathbf{x}) \partial_t S^\alpha(\mathbf{x}, p) + \operatorname{div}(\mathbf{q}^\alpha) = 0, \quad \alpha = 1, 2.$$

- Incompressible flow
- Immiscible flow

# Equi-dimensional model: matrix and fracture domains



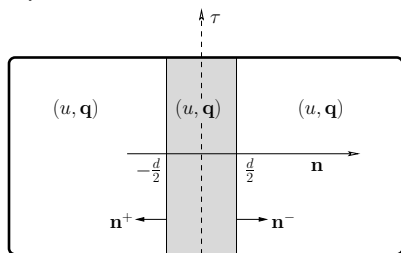
- Fracture: can act as drain or barrier
- Fracture width:  $d_f \ll$  matrix size  $L$
- Fracture rocktype (f):  $\Lambda_f, k_f^\alpha, S_f^\alpha$
- Matrix rocktype (m):  $\Lambda_m, k_m^\alpha, S_m^\alpha$



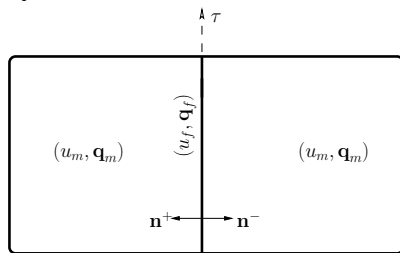
# Dimensional Hybridizing (codimension 1 in the fracture)

- **Dimensional hybridizing:** averaging the model equations over the fracture width
- **Objectives:** facilitate the mesh generation and lower the number of degrees of freedom

equi-dimensional model:



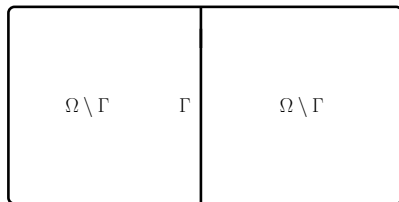
hybrid-dimensional model:



# Dimensional Hybridizing

- Continuous pressure models (pervious fractures):  
[Granet et al 2001], [Jaffré et al. 2002], [Bogdanov et al 2003],  
[Karimi Fard 2004], [Bastian et al 2006], [Brenner et al 2014]
- Discontinuous pressure models (pervious fractures or barriers):  
[Faille et al 2003], [Jaffré et al. 2005], [Firoozabadi et al 2008],  
[Angot et al 2009], [Brenner et al 2016]
- Objectives:
  - Derive hybrid dimensional two phase flow models
  - Discretization using the VAG scheme
  - Compare the equi-dimensional and hybrid dimensional models

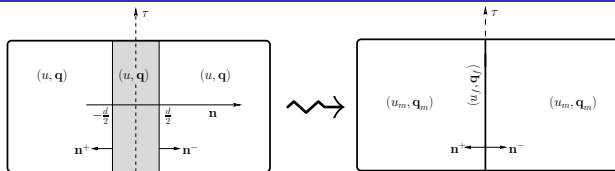
# Dimensional Hybridizing: matrix domain



- Equations in the matrix domain  $\Omega \setminus \Gamma$ :

$$\left\{ \begin{array}{l} \text{Darcy law with gravity: } \mathbf{q}_m^\alpha = -k_m^\alpha(S_m^\alpha(p_m)) \Lambda_m(\nabla u_m^\alpha - \rho^\alpha \mathbf{g}), \\ \text{Volume conservation: } \phi_m \partial_t S_m^\alpha(p_m) + \text{div}(\mathbf{q}_m^\alpha) = 0, \end{array} \right.$$

# Dimensional Hybridizing: averaging over the fracture width



- Phase superscript  $\alpha$  dropped

$$\Lambda_f = \begin{pmatrix} \Lambda_{f,\tau} & 0 \\ 0 & \Lambda_{f,n} \end{pmatrix} \text{ in } (\tau, n) \text{ coordinates}$$

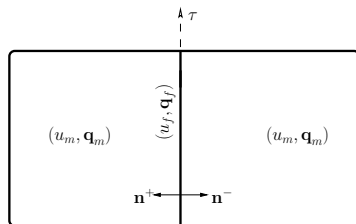
$$\mathbf{q} = -k_f(S_f(p)) \Lambda_f (\nabla u - \rho \mathbf{g})$$

$$= \underbrace{-k_f(S_f(p)) \Lambda_{f,\tau} (\nabla_\tau u - \rho \mathbf{g}_\tau)}_{\text{tangential flux } \mathbf{q}_\tau} \quad \underbrace{-k_f(S_f(p)) \Lambda_{f,n} (\partial_n u - \rho \mathbf{g} \cdot \mathbf{n})}_{\text{normal flux } (\mathbf{q} \cdot \mathbf{n}) \mathbf{n}}$$

# Dimensional Hybridizing: Fracture Equations

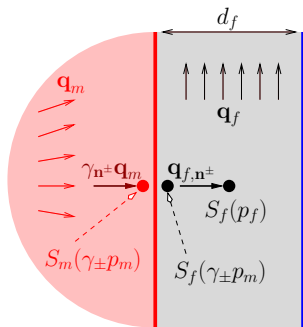
- $u_f = \frac{1}{d_f} \int_{-\frac{d_f}{2}}^{\frac{d_f}{2}} u \, dn; \quad S_f(p_f) \approx \frac{1}{d_f} \int_{-\frac{d_f}{2}}^{\frac{d_f}{2}} S_f(p) \, dn$
- $\mathbf{q}_f = \int_{-\frac{d_f}{2}}^{\frac{d_f}{2}} \mathbf{q}_\tau \, dn \approx -d_f k_f(S_f(p_f)) \Lambda_{f,\tau} (\nabla_\tau u_f - \rho \mathbf{g}_\tau) \quad (\text{Darcy Law})$
- $-d_f \phi_f \partial_t S_f(p_f) \approx \int_{-\frac{d_f}{2}}^{\frac{d_f}{2}} \text{div}(\mathbf{q}) \, dn = \text{div}_\tau(\mathbf{q}_f) + \left[ \mathbf{q} \cdot \mathbf{n} \right]_{-\frac{d_f}{2}}^{\frac{d_f}{2}}$   
 $= \text{div}_\tau(\mathbf{q}_f) + \gamma_{n^+} \mathbf{q}_m + \gamma_{n^-} \mathbf{q}_m \quad (\text{Conservation Equation})$

# Hybrid dimensional models: Summary ( $\alpha$ dropped)



$$\left\{ \begin{array}{l} \text{Matrix Darcy Law: } \mathbf{q}_m = -k_m(S_m(p_m)) \Lambda_m(\nabla u_m - \rho \mathbf{g}) \\ \text{Matrix Conserv. Eq.: } \phi_m \partial_t S_m(p_m) + \text{div}(\mathbf{q}_m) = 0 \\ \text{Fracture Darcy Law: } \mathbf{q}_f = -d_f k_f(S_f(p_f)) \Lambda_{f,\tau}(\nabla_\tau u_f - \rho \mathbf{g}_\tau) \\ \text{Fracture Conserv. Eq.: } \phi_f \partial_t S_f(p_f) + \text{div}_\tau(\mathbf{q}_f) + \gamma_{n^+} \mathbf{q}_m + \gamma_{n^-} \mathbf{q}_m = 0 \end{array} \right.$$

# Transmission conditions at the matrix fracture interface



## ■ Discontinuous pressure model:

$$\gamma_{n^{\pm}} \mathbf{q}_m = \mathbf{q}_{f,n^{\pm}} \approx$$

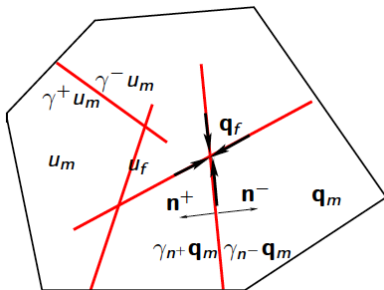
$$k_f(S_f(\gamma_{\pm} p_m)) \Lambda_{f,n} \left( \frac{\gamma_{\pm} u_m - u_f}{\frac{d_f}{2}} - \rho \mathbf{g} \cdot \mathbf{n}^{\pm} \right)^{+}$$

$$+ k_f(S_f(p_f)) \Lambda_{f,n} \left( \frac{\gamma_{\pm} u_m - u_f}{\frac{d_f}{2}} - \rho \mathbf{g} \cdot \mathbf{n}^{\pm} \right)^{-}$$

## ■ Continuous pressure model $\left( \frac{\Lambda_{f,n}}{d_f} \gg \frac{\Lambda_{m,n}}{L} \right)$ :

$$\gamma_{+} u_m = \gamma_{-} u_m = u_f.$$

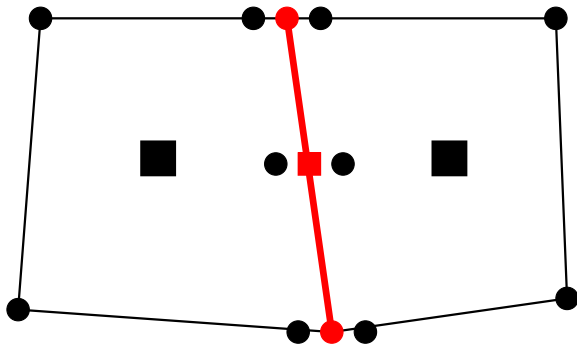
# Generalization to complex Discrete Fracture Network



- Pressure continuity and flux conservation is assumed at fracture intersections
- Zero flux is assumed at immersed fracture tips

# The Vertex Approximate Gradient Discretization (VAG)

# Degrees of Freedom (discontinuous pressure model)



- Two matrix cells touching a fracture face
  - Matrix d.o.f. (black)
  - Fracture d.o.f. (red)

# VAG Matrix-Matrix and Fracture-Fracture Fluxes

## ■ mm (ff) fluxes:

- upwind (w.r.t. the phase mobility)
- MPFA
- local stencil to each cell  $K$   
(fracture face  $\sigma$ )

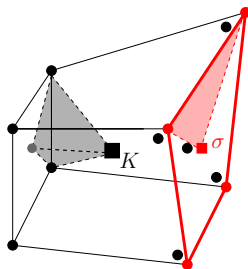
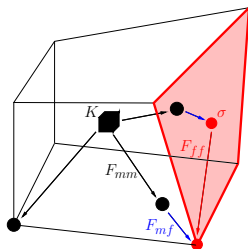
$$F_{K\nu}(u) = k_m(S_m(p_K))f_{K\nu}(u)^+ + k_m(S_m(p_\nu))f_{K\nu}(u)^-$$

$$f_{K\nu}(u) = \sum_{\nu' \in \partial K} T_K^{\nu\nu'} (u_K - u_{\nu'} - \rho(\mathbf{x}_K - \mathbf{x}_{\nu'}) \cdot \mathbf{g})$$

## ■ mm (ff) transmissivities:

- conforming  $P^1$  FE gradient on a tetrahedral (triangular) submesh ( $\{\mathbf{e}_\nu\}_\nu = P^1$  FE Basis Functions)

$$T_K^{\nu\nu'} = \int_K \Lambda \nabla \mathbf{e}_\nu \nabla \mathbf{e}_{\nu'} dx$$



# VAG Matrix-Fracture Fluxes

## mf fluxes:

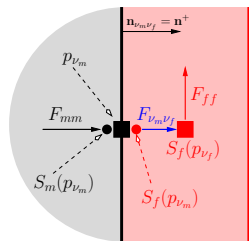
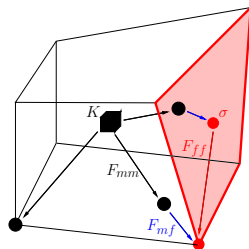
- upwind (w.r.t. the phase mobility)
- TPFA
- Saturation jump at mf interfaces
- Gravity in normal direction

$$F_{\nu_m \nu_f}(u) = k_f(S_f(p_{\nu_m}))f_{\nu_m \nu_f}(u)^+ + k_f(S_f(p_{\nu_f}))f_{\nu_m \nu_f}(u)^-$$

$$f_{\nu_m \nu_f}(u) = T_{\nu_m \nu_f}(u_{\nu_m} - u_{\nu_f} - \frac{\rho d_f}{2} \mathbf{g} \cdot \mathbf{n}_{\nu_m \nu_f})$$

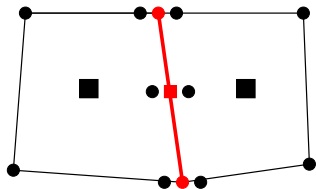
## mf transmissivities:

- Mass Lumping of  $P^1$  FE basis function traces

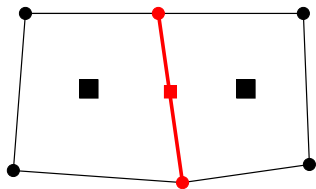


# Hybrid Continuous Pressure and Hybrid Discontinuous Pressure degrees of freedom

- Hybrid Discontinuous Pressure



- Hybrid Continuous Pressure



# Hybrid Continuous Pressure model: Fluxes

## Matrix mm fluxes

$$F_{K\nu}(u) = k_m(S_m(p_K))f_{K\nu}(u)^+ + k_m(S_m(p_\nu))f_{K\nu}(u)^-$$

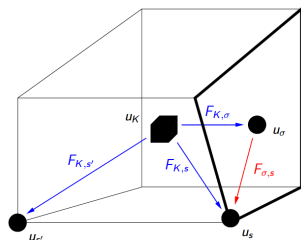
$$f_{K\nu}(u) = \sum_{\nu' \in \partial K} T_K^{\nu\nu'} (u_K - u_{\nu'} - \rho(\mathbf{x}_K - \mathbf{x}_{\nu'}) \cdot \mathbf{g})$$

## Fracture ff fluxes

$$F_{\sigma s}(u) = k_f(S_f(p_\sigma))f_{\sigma s}(u)^+ + k_f(S_f(p_s))f_{\sigma s}(u)^-$$

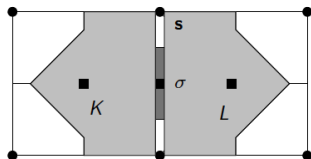
$$f_{\sigma s}(u) = \sum_{s' \in \partial\sigma} T_\sigma^{ss'} (u_\sigma - u_{s'} - \rho(\mathbf{x}_\sigma - \mathbf{x}_{s'}) \cdot \mathbf{g})$$

## No mf fluxes

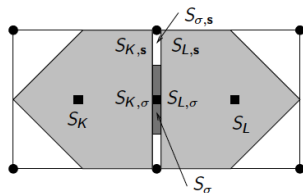


# Hybrid Continuous Pressure model

## Control Volumes



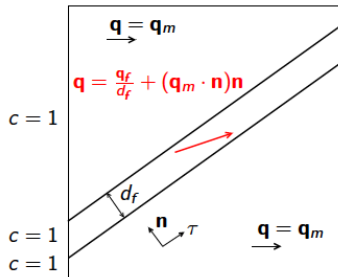
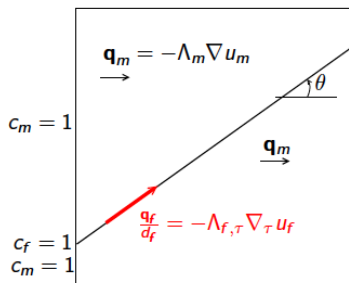
## Saturations at matrix fracture interfaces



$$\left\{ \begin{array}{l} S_{K,\nu}^\alpha = S_m^\alpha(p_\nu), \\ S_K^\alpha = S_m^\alpha(p_K), \end{array} \right. \quad \left\{ \begin{array}{l} S_{\sigma,s}^\alpha = S_f^\alpha(p_s), \\ S_\sigma^\alpha = S_f^\alpha(p_\sigma). \end{array} \right.$$

# Numerical Results

# Comparison of equi- and hybrid-dimensional models: tracer equation



$$\text{Hyb. dim.:} \quad \begin{cases} \partial_t c_m + \text{div}(c_m \mathbf{q}_m) = 0, \\ d_f \partial_t c_f + \text{div}_{\tau}(c_f \mathbf{q}_f) + \gamma_{n^+}(c_m \mathbf{q}_m) + \gamma_{n^-}(c_m \mathbf{q}_m) = 0, \\ \gamma_{n^{\pm}}(c_m \mathbf{q}_m) = c_f (\gamma_{n^{\pm}} \mathbf{q}_m)^+ + (\gamma_{\pm} c_m) (\gamma_{n^{\pm}} \mathbf{q}_m)^-. \end{cases}$$

$$\text{Equi dim.:} \quad \partial_t c + \text{div}(c \mathbf{q}) = 0.$$

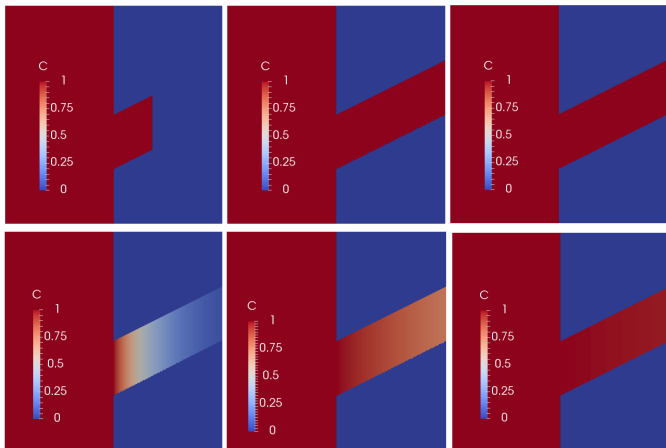
# Comparison of equi- and hybrid-dimensional tracer solutions in the matrix at $t = 0.5$

$d_f = 0.001$ ,  $\Lambda_m = 1$ , and  $\Lambda_{f,\tau} = 100, 1000$  and  $10000$ .

$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 0.1$$

$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 1$$

$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 10$$



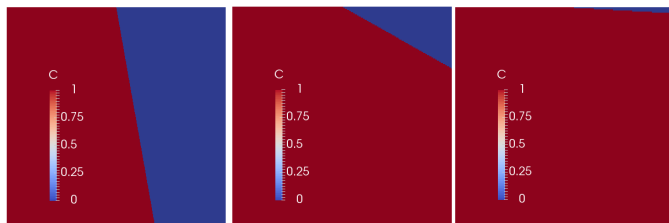
# Equi dimensional solution in the fracture at time $t = 0.5$

$d_f = 0.001$ ,  $\Lambda_m = 1$ , and  $\Lambda_{f,\tau} = 100, 1000$  and  $10000$ .

$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 0.1$$

$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 1$$

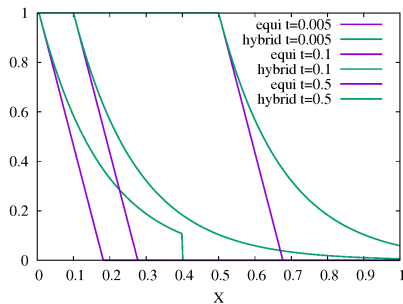
$$\frac{\Lambda_{f,\tau} d_f}{\Lambda_m L} = 10$$



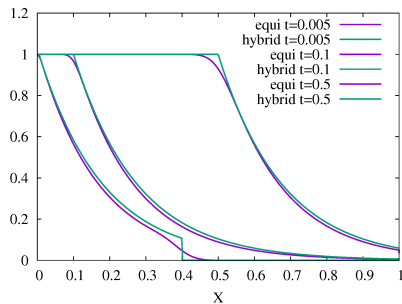
# Equi dimensional solutions in the fracture with and without normal diffusion in the fracture

$$\partial_t c + \operatorname{div}(c\mathbf{q} - D_{f,n}\mathbf{1}_{\Omega_f}\mathbf{n} \otimes \mathbf{n}\nabla c) = 0.$$

$$\frac{\Lambda_{f,\tau}d_f}{\Lambda_m L} = 1, \quad \frac{D_{f,n}}{d_f|q_m \cdot \mathbf{n}|} = 0$$



$$\frac{\Lambda_{f,\tau}d_f}{\Lambda_m L} = 1, \quad \frac{D_{f,n}}{d_f|q_m \cdot \mathbf{n}|} = \sqrt{5}$$



# Comparison of equi- and hybrid-dimensional models: two phase flow

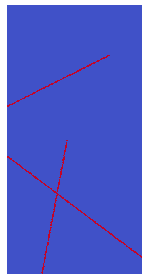
- $\Omega = (0, 400) \times (0, 800)$  m
- Equi-dimensional mesh: 22500 triangles
- Hybrid dimensional mesh: 16900 triangles
- **Matrix:**

$$\phi_m = 0.2, \quad \Lambda_m \text{ isotropic}$$

- **Faults:**

$$d_f = 4m, \quad \phi_f = 0.4, \quad \Lambda_f \text{ isotropic}$$

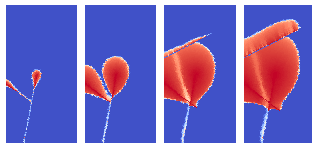
- Injection of oil in the bottom fault
- Initially saturated with water



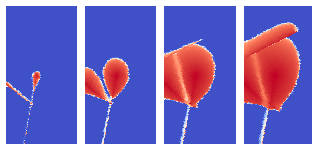
Drains:  $\Lambda_f/\Lambda_m = 1000$ ;  $p_{c,m}(S_m^o) = p_{c,f}(S_f^o) = 0$

**Zero Capillary Pressure:**  $p_{c,m}(S_m^o) = p_{c,f}(S_f^o) = 0$

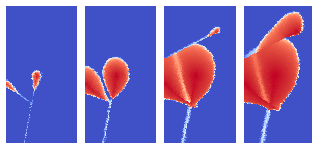
■ Equi dim



■ Hybrid Disc.



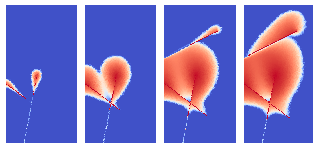
■ Hybrid Cont.



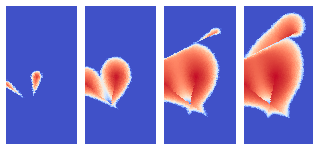
Drains:  $\Lambda_f/\Lambda_m = 1000$ ;  $p_{c,m} \neq 0$ ;  $p_{c,f} = 0$

**Capillary Pressure:**  $p_{c,m}(S_m^o) = -10^5 \ln(S_m^o)$ ;  $p_{c,f} = 0$

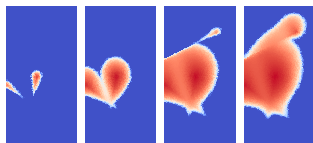
■ Equi dim



■ Hybrid Disc.

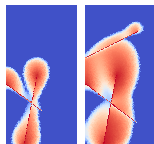


■ Hybrid Cont.

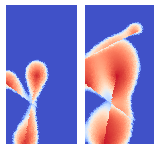


Drains:  $\Lambda_f/\Lambda_m = 100$ ;  $p_{c,m} = -10^5 \ln(S_m^o)$ ,  
 $p_{c,f} = -10^4 \ln(S_m^o)$

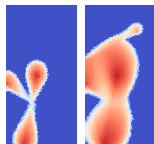
■ Equi dim



■ Hybrid Disc.



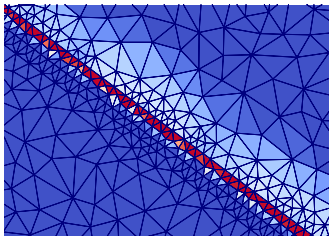
■ Hybrid Cont.



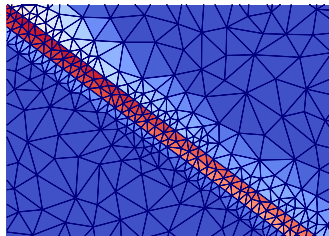
Drains:  $\Lambda_f/\Lambda_m = 100$ ;  $p_{c,m} = -10^5 \ln(S_m^o)$

Equi-Dimensional Model: Saturation Stratification in the fault Network

$$p_{c,f} = 0$$



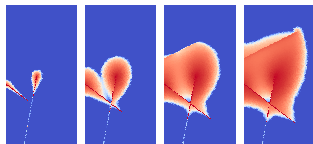
$$p_{c,f} = -10^4 \ln(S_m^o)$$



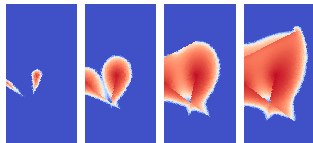
Drain-Barrier:  $\Lambda_f^{drain} / \Lambda_m = 1000$ ;  $\Lambda_f^{barrier} / \Lambda_m = 0.01$

**Capillary Pressure:**  $p_{c,m} = -10^5 \ln(S_m^o)$ ;  $p_{c,f} = 0$

■ Equi dim

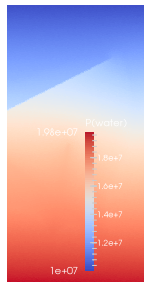


■ Hybrid Disc.

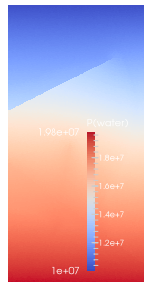


Drain-Barrier:  $\Lambda_f^{drain} / \Lambda_m = 1000$ ;  $\Lambda_f^{barrier} / \Lambda_m = 0.01$

Equi dim.



Hybrid Disc.



# Computational Performance

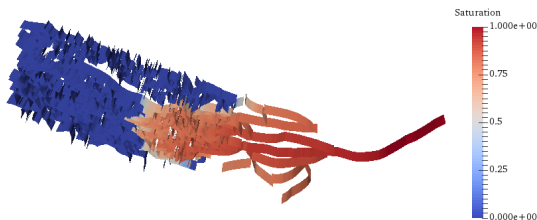
Model	CPU
Test Drains: $\Lambda_f/\Lambda_m = 1000$ ; $p_{c,m} = p_{c,f} = 0$	
equi dim.	9024
disc. hybrid	2951
cont. hybrid	960
Test Drains: $\Lambda_f/\Lambda_m = 1000$ ; $p_{c,m} \neq 0$ ; $p_{c,f} = 0$	
equi dim.	30697
disc. hybrid	4123
cont. hybrid	1022
Test Drains: $\Lambda_f/\Lambda_m = 100$ ; $p_{c,m} \neq 0$ ; $p_{c,f} \neq 0$	
equi dim.	2213
disc. hybrid	876
cont. hybrid	602
Test Drain-Barrier	
equi dim.	24199
disc. hybrid	3546

# Conclusion

- Two phase flow hybrid discontinuous dimensional model taking into account
  - networks of fractures
  - drains and barriers
  - discontinuous capillary pressures
  - gravity
- Numerical experiments and comparisons with the hybrid continuous model show that
  - the model takes into account barriers
  - the model is more accurate even for pervious fractures, especially for gravity dominant flows
  - the model is more expensive due to smaller control volumes at the matrix fracture interfaces

# Perspectives

- Better compromise accuracy - CPU time: “remove” the small control volumes at the mf interfaces
- Convergence analysis using the gradient scheme framework (with J. Droniou)
- Large 3D networks: HPC with F. Xing and BRGM
- More complex physics: geothermal flows with F. Xing and BRGM



# Acknowledgements

Thanks for your attention and thanks to Total S.A. for supporting this work.

