

FEM Exercise 3: A first FEM code

Let us consider the problem $-\alpha u'' + \beta u = f$, in $]0, 1[$ with $\alpha, \beta > 0$, $f \in L^2(]0, 1[)$ and boundary conditions $u(0) = 0$, $u(1) = 0$.

2.1. Compute the analytical solution of the considered problem.

The characteristic equation associated to the corresponding homogeneous equation is $-\alpha r^2 + \beta = 0$, whose roots are $r_{1,2} = \pm \sqrt{\frac{\beta}{\alpha}}$. The corresponding solution is then $u(x) = c_1 \exp(r_1 x) + c_2 \exp(r_2 x)$.

Let ϕ_1 and ϕ_2 be the functions $\phi_1(x) = \exp(r_1 x)$ and $\phi_2(x) = \exp(r_2 x)$. The solution for the non-homogeneous equation is the following

$$u(x) = c_1(x) \phi_1(x) + c_2(x) \phi_2(x), \quad (0.1)$$

where the functions c'_1 and c'_2 are solutions of the linear system

$$\begin{cases} c'_1(x) \phi_1(x) + c'_2(x) \phi_2(x) = 0, \\ c'_1(x) \phi'_1(x) + c'_2(x) \phi'_2(x) = \frac{f(x)}{\alpha}. \end{cases}$$

One gets

$$\begin{cases} c'_1(x) = \frac{-\frac{f(x)}{\alpha} \phi_2(x)}{\phi_1(x) \phi'_2(x) - \phi'_1(x) \phi_2(x)} = \frac{-\frac{f(x)}{\alpha} \exp\left(\sqrt{\frac{\beta}{\alpha}} x\right)}{2 \sqrt{\frac{\beta}{\alpha}}}, \\ c'_2(x) = \frac{\frac{f(x)}{\alpha} \phi_1(x)}{\phi_1(x) \phi'_2(x) - \phi'_1(x) \phi_2(x)} = \frac{\frac{f(x)}{\alpha} \exp\left(-\sqrt{\frac{\beta}{\alpha}} x\right)}{2 \sqrt{\frac{\beta}{\alpha}}}. \end{cases}$$

Then integrating the above equations over $(0, x)$ where $x \in (0, 1)$ one obtains

$$\begin{cases} c_1(x) = c_1(0) + \int_0^x \frac{-\frac{f(s)}{\alpha} \exp\left(\sqrt{\frac{\beta}{\alpha}} s\right)}{2 \sqrt{\frac{\beta}{\alpha}}} ds, \\ c_2(x) = c_2(0) + \int_0^x \frac{\frac{f(s)}{\alpha} \exp\left(-\sqrt{\frac{\beta}{\alpha}} s\right)}{2 \sqrt{\frac{\beta}{\alpha}}} ds. \end{cases}$$

The constants $c_1(0)$ and $c_2(0)$ are computed by using the boundary conditions $u(0) = 0$ and $u(1) = 0$ after substituting $c_1(x)$ and $c_2(x)$ in (0.1).

2.2. State the variational formulation of the proposed problem and prove the existence and the uniqueness of a weak solution.

Let $a : (u, v) \mapsto \alpha \int_0^1 u'v' dx + \beta \int_0^1 uv dx$ and $L : v \mapsto \int_0^1 fv dx$. Set $V = H_0^1(0, 1) = \{v \in H^1(0, 1), v(0) = v(1) = 0\}$.

The variational formulation is the following:

find $u \in V$ such that $a(u, v) = L(v), \forall v \in V$.

- The space $V = H_0^1(0, 1)$ is a hilbert since $V = Ker\gamma$, is closed, where γ is the trace function $\gamma : H^1(0, 1) \rightarrow L^2(\{0, 1\}), v \mapsto \{v(0), v(1)\}$, which is continuous.
- The bilinear form a is continuous :

$$\begin{aligned} |a(u, v)| &\leq \alpha \left| \int_0^1 u'v' dx \right| + \beta \left| \int_0^1 uv dx \right| \\ &\leq \alpha \|u'\|_2 \|v'\|_2 + \beta \|u\|_2 \|v\|_2 \\ &\leq \max(\alpha, \beta) \left| \begin{pmatrix} \|u\|_2 \\ \|u'\|_2 \end{pmatrix} \cdot \begin{pmatrix} \|v\|_2 \\ \|v'\|_2 \end{pmatrix} \right| \\ &\leq \max(\alpha, \beta) \left\| \begin{pmatrix} \|u\|_2 \\ \|u'\|_2 \end{pmatrix} \right\|_{2, \mathbb{R}^2} \left\| \begin{pmatrix} \|v\|_2 \\ \|v'\|_2 \end{pmatrix} \right\|_{2, \mathbb{R}^2} \\ &= \max(\alpha, \beta) \left(\|u\|_2^2 + \|u'\|_2^2 \right)^{1/2} \left(\|v\|_2^2 + \|v'\|_2^2 \right)^{1/2} \\ &= \max(\alpha, \beta) \|u\|_{H^1(0,1)} \|v\|_{H^1(0,1)}. \end{aligned}$$

- The bilinear form a is coercive :

$$\begin{aligned} a(u, u) &= \alpha \left| \int_0^1 u'^2 dx \right| + \beta \left| \int_0^1 u^2 dx \right| \\ &\geq \min(\alpha, \beta) \left(\int_0^1 u'^2 dx + \int_0^1 u^2 dx \right) = \min(\alpha, \beta) \|u\|_{H^1(0,1)}^2. \end{aligned}$$

- The linear form L is continuous on V :

$$|L(v)| = \left| \int_0^1 fv dx \right| \leq \|f\|_2 \|v\|_2 \leq \|f\|_2 \|v\|_{H^1(0,1)}.$$

Thanks to Lax-Milgram theorem, there exists a unique u that solves the variational formulation.

2.3. Let us consider a uniform mesh over the interval $[0, 1]$ with $N + 1$ nodes and elements of length h . Write the space V_h for a piece-wise linear FE approximation of the weak problem and the discrete problem to solve in V_h .

Let \mathcal{P}_1 be the set of polynomials of degree less than or equal to 1 in the variable $x \in \mathbb{R}$, $C^0([0, 1])$ the set of continuous functions on the closed interval $[0, 1]$. Then the set V is the following

$$V = \{v \in C^0([0, 1]), v|_{[x_i, x_{i+1}]} \in \mathcal{P}_1, i = 1, \dots, n, v(0) = v(1) = 0\}.$$

2.4. Prove that $V_h \subset H_0^1(]0, 1[)$.

- Let $v \in V_h$. Then $v(0) = v(1) = 0$. Moreover $v \in L^2(0, 1)$ since $v \in C^0([0, 1])$.
- Let $v \in V_h$. Since $v|_{[x_i, x_{i+1}]} \in \mathcal{P}_1$, its derivative in classical sens on each interval $[x_i, x_{i+1}]$ belongs to \mathcal{P}_1 . Let $w_i = v'|_{[x_i, x_{i+1}]}$. For $\phi \in \mathcal{D}(\Omega)$, we have

$$\begin{aligned} \langle v', \phi \rangle &= -\langle v, \phi' \rangle \\ &= -\int_0^1 v \phi' dx \\ &= -\sum_{i=1}^n \int_{x_i}^{x_{i+1}} v \phi' dx \\ &= -\sum_{i=1}^n [v \phi]_{x_i}^{x_{i+1}} + \sum_{i=1}^n \int_{x_i}^{x_{i+1}} v' \phi dx \\ &= v(x_1) \phi(x_1) - v(x_{N+1}) \phi(x_{N+1}) + \sum_{i=1}^n \int_0^1 w_i \phi' dx \\ &= \langle w, \phi \rangle, \end{aligned}$$

where w is defined by $w_i = w|_{[x_i, x_{i+1}]}$. Since $w \in L^2(0, 1)$, $v \in H^1(0, 1)$.

2.5. Prove the existence and uniqueness of the discrete solution $u_h \in V_h$.

The discrete problem is

$$\text{find } u_h \in V \text{ such that } a(u_h, v_h) = L(v_h), \forall v_h \in V_h.$$

By taking $v_h = \phi_i, i = 1, \dots, N+1$ and $u_h = \sum_{j=1}^{N+1} u_{h_j} \phi_j$, one gets $a(u_h, \phi_i) = \sum_{j=1}^{N+1} u_{h_j} a(\phi_j, \phi_i) = L(\phi_i), i = 1, \dots, N+1$, which is a linear system. Let A be the matrix $A = (a(\phi_i, \phi_j))_{i,j=1, \dots, N+1}$

and u_h^{N+1} the vector $u_h^{N+1} = \begin{pmatrix} u_{h_1} \\ \vdots \\ u_{h_j} \\ \vdots \\ u_{h_{N+1}} \end{pmatrix}$. Then to prove the existence and uniqueness

of u_h , it amounts to prove that A is invertible, which becomes to prove that $Au_h^{N+1} = 0$ leads to $u_h^{N+1} = 0$. Since $Au_h^{N+1} = 0$ implies $a(u_h, u_h) = (Au_h^{N+1}, u_h^{N+1}) = 0$, one gets $0 = a(u_h, u_h) \geq \min(\alpha, \beta) \|u\|_{H^1(0,1)}^2$ because a is coercive on $V_h \subset V$. This leads to $u_h = 0$ which turns into $u_h^{N+1} = 0$.

2.6. Prove that there exists a unique function $\varphi_i \in V_h$ such that $\varphi_i(x_j) = \delta_{ij}$,

$i, j = 1, N + 1$ and that $\{\varphi_i\}_{i=1, N+1}$ is a basis of V_h . Give the expression of φ_i , for a generic index i .

Let W be the space generated by the family $\{\varphi_i\}_{i=1, N+1}$.

• One has $W \subset V_h$: let $w = \sum_{i=1}^{N+1} \alpha_i \phi_i \in W$ where $\alpha_i \in \mathbb{R}$. Then one has $w(0) = w(1) = 0$. Since $\phi_i \in \mathcal{P}_\infty$, one has $\phi_i \in H^1(0, 1)$, finally $w \in V_h$.

• One has $V_h \subset W$. Indeed let $v_h \in V_h$. We set $w = \sum_{i=1}^{N+1} v_h(x_i) \phi_i$. Clearly one has $w \in W$. Moreover, in each interval $[x_i, x_{i+1}]$, $i = 1, \dots, n$, w and v_h belong to \mathcal{P}_1 and coincide in two points, $w(x_i) = v_h(x_i)$, $w(x_{i+1}) = v_h(x_{i+1})$. The functions w and v_h are equal on the all intervalls $[x_i, x_{i+1}]$, $i = 1, \dots, n$, then $w = v_h$ on $(0, 1)$.

• The family ϕ_i , $i = 1, \dots, n$, is linearly independent. Let $0 = w = \sum_{i=1}^{N+1} \alpha_i \phi_i$ where α_i are scalars. Since $w(x_j) = \sum_{i=1}^{N+1} \alpha_i \phi_i(x_j) = \alpha_j \phi_j(x_j) = \alpha_j$, on has $\alpha_i = 0$, $i = 1, \dots, n$. Hence $\{\varphi_i\}_{i=1, N+1}$ is a basis of V_h .

The functions ϕ_i are given by

$$\begin{aligned} \bullet \phi_1(x) &= \begin{cases} \frac{x_2 - x}{h} & \text{if } x \in [x_1, x_2], \\ 0 & \text{otherwise,} \end{cases} \\ \bullet \phi_i(x) &= \begin{cases} \frac{x - x_{i-1}}{h} & \text{if } x \in [x_{i-1}, x_i], \\ \frac{x_{i+1} - x}{h} & \text{if } x \in [x_i, x_{i+1}], \\ 0 & \text{otherwise,} \end{cases} \quad \text{for } i = 2, \dots, N, \\ \bullet \phi_{N+1}(x) &= \begin{cases} \frac{x - x_N}{h} & \text{if } x \in [x_N, x_{N+1}], \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

2.7. Compute the local stiffness and mass matrices on a mesh element, with α and β equal to 1.

Let us consider the i th element $[x_i, x_{i+1}]$ where $i = 1, \dots, N$. The local stiff matrix $(a_{lk})_{l,k=1,2}$ entries are given by

$$\begin{aligned} a_{11} &= \alpha \int_{x_i}^{x_{i+1}} \phi'_i(x) \phi'_i(x) dx = \frac{\alpha}{h}, & a_{12} &= \alpha \int_{x_i}^{x_{i+1}} \phi'_i(x) \phi'_{i+1}(x) dx = -\frac{\alpha}{h}, \\ a_{21} &= \alpha \int_{x_i}^{x_{i+1}} \phi'_{i+1}(x) \phi'_i(x) dx = -\frac{\alpha}{h}, & a_{22} &= \alpha \int_{x_i}^{x_{i+1}} \phi'_{i+1}(x) \phi'_{i+1}(x) dx = \frac{\alpha}{h}, \end{aligned}$$

which gives

$$(a) = \frac{1}{h} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}.$$

The local mass matrix $(m_{lk})_{l,k=1,2}$ entries are given by

$$m_{11} = \beta \int_{x_i}^{x_{i+1}} \phi_i(x) \phi_i(x) dx = \frac{\beta}{3} h, \quad m_{12} = \beta \int_{x_i}^{x_{i+1}} \phi_i(x) \phi_{i+1}(x) dx = \frac{\beta}{6} h,$$
$$m_{21} = \beta \int_{x_i}^{x_{i+1}} \phi_{i+1}(x) \phi_i(x) dx = \frac{\beta}{6} h, \quad m_{22} = \beta \int_{x_i}^{x_{i+1}} \phi_{i+1}(x) \phi_{i+1}(x) dx = \frac{\beta}{3} h,$$

which leads to

$$(m) = \frac{\beta}{3} h \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}.$$

2.8. Let us now write a code in Scilab to compute explicitly the discrete solution on the given mesh and evaluate the method convergence rate with respect to $h \rightarrow 0$ in different norms. Let us consider $f(x) = x^2$. The program can be structured as follows:

1. Define the mesh (number of nodes, number of elements, size h of the mesh elements, coordinates of the mesh nodes, connectivity of the mesh elements).
2. Dimension and initialize to zero of the global arrays A , F , U , E .
3. Loop on the element: for each element
 - Use the local stiffness and mass matrices on a mesh element, computed in **2.3**. Are these matrices different from one element to the other ?
 - Compute the local right-hand side by using the (Gauss Legendre) two-point quadrature formula over $[-1, 1]$, with nodes $\hat{x}_i = \pm 1/\sqrt{3}$ and weights $\hat{w}_i = 1$.
 - Assemble the local contributions into the global arrays by using the element connectivity.
4. Impose the boundary conditions on the system matrix and right-hand side.
5. Solve the (discrete problem) linear system by the command $U = A \setminus F$.
6. Visualize the results by the command $\text{plot}(x,U)$, where the x vector contains the coordinates of the mesh nodes and U the solution approximated value at them.
7. Compute the error in the L^∞ - and L^2 -norms for h , $h/2$, $h/4$, $h/8$, by using the analytical solution computed in **2.1** and visualize the error in a log-log plot.