



Abstract

Let M be a compact manifold and P a manifold diffeomorphic to M . Let c be a two point real function defined on an open subset $\Omega(c)$ of $M \times P$ that projects onto M and P . Given a probability volume measure μ on M and another such one ϖ on P , we assume the non-emptiness of the set $\text{Diff}(\mu, \varpi, c)$ of diffeomorphisms from M to P that push μ to ϖ and have their graph lying $\Omega(c)$. Following Monge [1], let us consider the transportation (or allocation) cost functional:

$$\phi \in \text{Diff}(\mu, \varpi, c) \rightarrow \mathcal{C}(\phi) = \int_M c(m, \phi(m)) d\mu.$$

If a diffeomorphism $\varphi \in \text{Diff}(\mu, \varpi, c)$ is *stationary* for the functional \mathcal{C} , we can find real functions $f(m)$ and $\tilde{f}(p)$ such that the two point function F given by $F(m, p) = c(m, p) + f(m) + \tilde{f}(p)$ is *stationary* at each point of the graph of φ . This variational heuristics is originally due to Appell [2]. If the *second* variation of the functional \mathcal{C} at φ is *nonnegative*, we can further show that the Hessian of the two point function F is *nonnegative* at each point of $\text{graph}(\varphi)$.

Geometric preliminary

A path $t \mapsto \phi_t \in \text{Diff}(\mu, \varpi, c)$ near $t = 0$ may be written $\phi_t = \xi_t \circ \varphi$, where $\varphi = \phi_0$ and $t \mapsto \xi_t$ is a path of ϖ -preserving diffeomorphisms of the target manifold P . This way of writing ϕ_t indicates that $\text{Diff}(\mu, \varpi, c)$ possesses a *manifold* structure locally modelled on that of the ϖ -preserving diffeomorphisms [3]. Accordingly, a tangent vector at the diffeomorphism $\varphi \in \text{Diff}(\mu, \varpi, c)$ is written $(V \circ \varphi)$ with $V \in \ker \text{div}_\varpi$. Similarly, setting $\tilde{c}(p, m) = c(m, p)$, we may consider the functional:

$$\psi \in \text{Diff}(\varpi, \mu, \tilde{c}) \rightarrow \tilde{\mathcal{C}}(\psi) = \int_P c(\psi(p), p) d\varpi(p),$$

and note that, if $\psi_0 = \varphi^{-1}$, the equality $\tilde{\mathcal{C}}(\psi_0) \equiv \mathcal{C}(\varphi)$ holds. A path $t \mapsto \psi_t \in \text{Diff}(\varpi, \mu, \tilde{c})$ near $t = 0$ is now written $\psi_t = \zeta_t \circ \varphi^{-1}$ with $\varphi^{-1} = \psi_0$ and $t \mapsto \zeta_t$ a path of μ -preserving diffeomorphisms of the source manifold M . A tangent vector to $\text{Diff}(\varpi, \mu, \tilde{c})$ at φ^{-1} reads $(U \circ \varphi^{-1})$ for some vector field U on M lying in $\ker \text{div}_\mu$.

Stationary condition

The first variation $\delta\mathcal{C}(\varphi)(V \circ \varphi)$ is equal to $\int_M d_{PC}(m, \varphi(m))(V(\varphi(m))) d\mu(m) \equiv \int_P \alpha(V) d\varpi$ where $\alpha(p) = d_{PC}(m, p)|_{m=\varphi^{-1}(p)}(V(p))$ is a 1-form on P . If this variation vanishes for each vector field $V \in \ker \text{div}_\varpi$, Helmholtz Lemma implies that the 1-form α is *exact*. So we can find a real function \tilde{f} on P such that the equation:

$$d_{PC}(m, p) + d\tilde{f}(p) = 0 \quad (1)$$

holds at each point (m, p) of the graph of the diffeomorphism φ . Dealing with the first variation $\delta\tilde{\mathcal{C}}(\varphi^{-1})(U \circ \varphi^{-1})$, with $U \in \ker \text{div}_\mu$, Helmholtz lemma yields similarly a real function f on M such that the equation:

$$d_M c(m, p) + df(m) = 0 \quad (2)$$

holds at each point (m, p) of $\text{graph}(\varphi)$. The two point function $F(m, p) = c(m, p) + f(m) + \tilde{f}(p)$ which we obtain is *stationary* at each point (m, p) of $\text{graph}(\varphi)$, as claimed.

Minimum condition

The integral of the two point function $(F - c)$ over the graph of the diffeomorphism $\phi_t \in \text{Diff}(\mu, \varpi, c)$ is independent of t , equal to $\int_M f d\mu + \int_P \tilde{f} d\varpi$. Therefore, the minimum condition $\delta^2\mathcal{C}(\varphi) \geq 0$ may be written equivalently:

$$\frac{d^2}{dt^2} \left(\int_M F(m, \phi_t(m)) d\mu \right)_{t=0} \geq 0. \quad (3)$$

The Hessian of the function $p \mapsto c(m, p) + \tilde{f}(p)$ at $p = \varphi(m)$ is *intrinsic* due to (1). We call it the c -Hessian of \tilde{f} at the point p , denote it by $\text{Hess}_c \tilde{f}(p)$. Moreover, from (1), the left-hand side of (3) reduces to $\int_P \text{Hess}_c \tilde{f}(V, V) d\varpi$, for some vector field $V \in \ker \text{div}_\varpi$. Altogether, the minimum condition $\delta^2\mathcal{C}(\varphi) \geq 0$ thus yields the inequality:

$$\int_P \text{Hess}_c \tilde{f}(V, V) d\varpi \geq 0, \quad \forall V \in \ker \text{div}_\varpi. \quad (4)$$

Similarly, we can define the c -Hessian of the function f at each point of M and the minimum condition $\delta^2\tilde{\mathcal{C}}(\varphi^{-1}) \geq 0$ implies:

$$\int_M \text{Hess}_c f(U, U) d\mu \geq 0, \quad (5)$$

for each vector field $U \in \ker \text{div}_\mu$.

Pointwise conditions

In [4], we proved that the inequalities (4) and (5) imply *pointwise* quadratic form inequalities:

$$\text{Hess}_c f \geq 0 \text{ and } \text{Hess}_c \tilde{f} \geq 0. \quad (6)$$

The proof goes by contradiction. If (6) does not hold for f (say), we can find a chart x of M pushing the measure $d\mu$ to the measure dx and such that the form $\text{Hess}_c f(U, U)$ reads *smaller* than the form: $-2(u^1)^2 + \sum_{i=2}^n (u^i)^2$, in a small enough cube $\{\max_i |x^i| < \varepsilon\}$ of size ε . The local vector field $w = x^1 \frac{\partial}{\partial x^2} - x^2 \frac{\partial}{\partial x^1}$ satisfies $\text{div} w = 0$ and its flow preserves any function of the form $h(x) = H(\sqrt{(x^1)^2 + (x^2)^2}, x^3, \dots, x^n)$, hence $\text{div}(hw) = 0$. Take $h(x) = \alpha(\sqrt{(x^1)^2 + (x^2)^2}) \prod_{i=3}^n \alpha(|x^i|)$, with α a cut-off function supported in the small interval $[0, \varepsilon]$. We get a *global* vector field $U = hw$ lying in $\ker \text{div}_\mu$. Moreover, the integral $\int_M \text{Hess}_c f(U, U) d\mu$ is less than $\int_{\mathbb{R}^n} h^2(x)((x^1)^2 - 2(x^2)^2) dx \leq -\pi \int_0^\varepsilon \alpha^2(r)r^3 dr$, which is *negative* contradicting (5).

Finally, the Hessian of the two point function F is itself *intrinsic* at each point of $\text{graph}(\varphi)$, since $dF = 0$ there. It vanishes along $\text{graph}(\varphi)$ while, transversally, in the direction of M , it coincides with $\text{Hess}_c f$. It is thus *nonnegative*, as claimed.

References

- [1] Gaspard Monge.
Mémoire sur la théorie des déblais et remblais.
Mémoires présentés par divers savants à l'Académie des Sciences de l'Institut de France. Académie Royale des Sciences de Paris, 1781.
- [2] Paul Appell.
Mémoire sur les déblais et les remblais des systèmes continus ou discontinus.
Mémoires présentés par divers savants à l'Académie des Sciences de l'Institut de France. Académie des Sciences de l'Institut National de France, 1887.
- [3] David G. Ebin and Jerrold Marsden.
Groups of diffeomorphisms and the motion of an incompressible fluid.
Ann. of Math. (2), 92:102–163, 1970.
- [4] Philippe P. Delanoë.
Second order variational heuristics for the Monge problem on compact manifolds.
Adv. Calc. Var., 5(3):329–344, 2012.